



| Candidate: | | | | Successful | |
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| Evalu | Evaluator: | | | nsuccessful | |
| Date: | · | | 1006 | 6-PROCESS-30 | |
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| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.1 | | | |
| Task | : | Direct a team in the operation of a rope victim stranded on or clinging to a natura high-angle environment | | | |
| Performance Outcome: | | Risks to victims and rescuers are minimized, injury to the victim is minimized, the means of attachment to the rope rescue system is maintained, and the victim is removed and brought to a safe area for transfer to EMS. | | | |
| Conditions: Given a victim stranded on or clinging to a feature and removal of the victim to the ground or other safe area | | | | means of | |
| Candidate Directive: | | "Using the provided victim and high-ang team to operate the rope rescue system | | | |
| | | | | | |
| NO. | | TASK STEPS | Successful | Unsuccessful | |
| 1 | Risks to | victims and rescuers were minimized | Cuccocciui | Choaccachai | |
| 2 | Injury to | the victim was minimized | | | |
| 3 | | ans of attachment to the rope rescue was maintained | | | |
| 4 | | m was removed and brought to a safe transfer to EMS | | | |
| Evalu | uator/Car | ndidate Comments: | | | |
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| Candidate: | | | | Successful | |
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| Evaluator: | | | | nsuccessful | |
| Data | | | 1006 | S-PROCESS-31 | |
| Date: | · | | | | |
| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.2 | | | |
| | | | | | |
| Task | : | Direct a team in the operation of a rope r victim suspended from rope or webbing i | • | | |
| Performance Outcome: | | Risks to victims and rescuers are minimized, injury to the victim is minimized, the means of attachment to the rope rescue system is maintained, the victim is removed from the rope or webbing, and the victim is brought to a safe area for transfer to EMS | | | |
| Cond | Given a victim suspended by a harness attached to anchored rope of webbing, systems for removal of the victim from the rope or webbing and a means of removal of the victim to the ground or other safe are | | | | |
| Candidate Directive: | | "Using the provided victim and high-angl team to operate the rope rescue system suspended from the rope/webbing". | | | |
| | | | | | |
| NO. | | TASK STEPS | | ST | |
| 1 | Risks to | victims and rescuers were minimized | Successful | Unsuccessful | |
| 2 | | the victim was minimized | | | |
| 3 | The mea | ins of attachment to the rope rescue | | | |
| 4 | The viction webbing | m was removed from the rope or | | | |
| 5 | The victim was brought to a safe area for transfer to EMS | | | | |
| Evalı | uator/Can | didate Comments: | | | |
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| Candidate: | | Successful L |
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| Evaluator: | | Unsuccessful |
| Date: | | 1006-PROCESS-32 |
| Standard: | NFPA 1006 – 2021 edition – 5.3.3 | |
| Task: | While suspended from a rope rescue system, victim suspended from rope or webbing in a has a separate rope rescue lowering or mechanical | igh-angle environment to |
| Performance Outcome: | Risks to victims and rescuers are minimized, movement during the transfer is minimized, the the rope rescue system is maintained, the victistatic line and lowered or raised to a stable sumanaged to reduce adverse effects associate induced injuries, selected specialized equipment victim movement, and the victim can be transprovider. | ne means of attachment to tim is removed from the urface, victim positioning is and with suspension- ent facilitates efficient |
| Conditions: | Given a rope rescue system, a specified minir the victim, victim transfer systems, and special necessary for the environment | |
| Candidate Directive: | "Using the provided victim and high-angle enveloped victim to the rope rescue system". | |

| NO. | TASK STEPS | TE | ST |
|-----|--|------------|--------------|
| NO. | IASK SIEPS | Successful | Unsuccessful |
| 1 | Risks to victims and rescuers were minimized | | |
| 2 | Undesirable victim movement during the transfer was minimized | | |
| 3 | The means of attachment to the rope rescue system was maintained | | |
| 4 | The victim was removed from the static line and lowered or raised to a stable surface | | |
| 5 | Victim positioning was managed to reduce adverse effects associated with suspension-induced injuries | | |
| 6 | Selected specialized equipment facilitated efficient victim movement | | |
| 7 | The victim could be transported to the local EMS provider. | | |



| Evaluator/Candidate Comments: | |
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| Cano | lidate: | | | Successful | | |
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| Evalu | uator: | | U | nsuccessful | | |
| Date | Date: | | | S-PROCESS-33 | | |
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| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.4 | | | | |
| Task: | | Perform the activities of a litter tender in a operation | a high-angle low | vering or raising | | |
| Performance Outcome: | | Risks to victims and rescuers are minimized; the means of attachment to the rope rescue system is secure; and the travel path is negotiated while minimizing risks to equipment or persons | | | | |
| Conditions: | | Given a rope rescue system, a specified minimum travel distance for the litter tender, life safety harnesses, litters, bridles, and specialized equipment necessary for the environment | | | | |
| Candidate Directive: | | "Using the provided rope rescue system as litter tender for a lowering or raising o | | operation, act | | |
| | | | , | | | |
| NO. | | TASK STEPS | Successful | ST Unsuccessful | | |
| 1 | Risks to | victims and rescuers were minimized | | | | |
| 2 | | ns of attachment to the rope rescue vas secure | | | | |
| 3 | | el path was negotiated while minimizing equipment or person | | | | |
| Eval | uator/Car | ndidate Comments: | | | | |
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| Cano | lidate: | | | Successful |
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| Evalu | uator: | | Uı | nsuccessful 🗌 |
| Date | : | | <u> </u> | 1006-SKILL-34 |
| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.5 | | |
| Task: Participate as a member of a team in the system intended to move a suspended repath to avoid an obstacle | | | | |
| Performance Outcome: | | Personnel assignments are made and cleasystem constructed can accommodate the the system will not exceed the rated capa parts; a system safety check is performed efficient; and loads can be held in place of over the required distance. | e load; tension a acity of any of its d; movement on | applied within components' the load is |
| Conditions: Given rescue personnel, life safety rope, rope rescue equipment, a suitable anchor capable of supporting the load | | | uipment, and a | |
| Candidate Directive: | | "Work with your team to construct a rope suspended rescue load along a horizontal | | |
| NO. | | TASK STEPS | TEST | |
| 140. | | | Successful | Unsuccessful |
| 1 | Personno commun | el assignments were made and clearly icated | | |
| 2 | The syst load | em constructed could accommodate the | | |
| 3 | Tension applied within the system would not exceed the rated capacity of any of its components' parts | | | |
| 4 | A system | n safety check was performed | | |
| 5 | Moveme | nt on the load was efficient | | |
| 6 | | ould be held in place or moved with effort over the required distance | | |

Revision Date: January 26, 2023

Evaluator/Candidate Comments:







| Candidate: | | | | Successful | |
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| Evaluator: | | | Uı | nsuccessful | |
| Date | : | | 1006 | -PROCESS-35 | |
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| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.6 | | | |
| Task: | | Direct a team in the operation of a rope system to move a suspended rescue load along a horizontal path | | | |
| Performance Outcome: | | The movement is controlled; the load is held in place when needed; operating methods do not stress the system to the point of failure; personnel assignments are made; tasks are communicated; and potential problems are identified, communicated, and managed. | | | |
| Cond | ditions: | Given rescue personnel, an established load to be moved, and PPE | system, a target | for the load, a | |
| Candidate Directive: | | "Direct your team to move the suspended load horizontally along the provided rope rescue system" | | | |
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| | | | TE | ST | |
| NO. | | TASK STEPS | TE Successful | ST Unsuccessful | |
| NO. | The mov | TASK STEPS rement was controlled | | | |
| | | | | | |
| 1 | The load Operatin | rement was controlled | | | |
| 1 2 | The load Operatin the point | rement was controlled was held in place when needed g methods did not stress the system to | | | |
| 1 2 3 | The load Operatin the point Personne | rement was controlled was held in place when needed g methods did not stress the system to of failure | | | |
| 1 2 3 4 | The load Operatin the point Personne Tasks we Potential | rement was controlled I was held in place when needed g methods did not stress the system to of failure el assignments were made | | | |
| 1 2 3 4 5 | The load Operatin the point Personne Tasks we Potential commun | rement was controlled I was held in place when needed g methods did not stress the system to of failure el assignments were made ere communicated I problems were identified, | | | |
| 1 2 3 4 5 | The load Operatin the point Personne Tasks we Potential commun | rement was controlled I was held in place when needed g methods did not stress the system to of failure el assignments were made ere communicated I problems were identified, icated, and managed | | | |
| 1 2 3 4 5 | The load Operatin the point Personne Tasks we Potential commun | rement was controlled I was held in place when needed g methods did not stress the system to of failure el assignments were made ere communicated I problems were identified, icated, and managed | | | |
| 1 2 3 4 5 | The load Operatin the point Personne Tasks we Potential commun | rement was controlled I was held in place when needed g methods did not stress the system to of failure el assignments were made ere communicated I problems were identified, icated, and managed | | | |





| Candidate: | | | | Successful |
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| Evalu | Evaluator: | | | nsuccessful |
| Date | : | | | 1006-SKILL-36 |
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| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.7 | | |
| Task: | | Climb and traverse natural features or management require the use of climbing aids, position systems to prevent the fall or unwanted | ing equipment, c | or fall protection |
| Performance Outcome: | | The objective is achieved, the rescuer can perform the required task, and fall protection is maintained. | | |
| Conditions: | | Given the equipment used by the agency, and a task that reflects the anticipated rescue environment | | |
| Candidate Directive: | | "Using the provided structure, climb and using any necessary climbing aids, posit protection systems". | | |
| | | | | |
| NO. | | TASK STEPS | Successful | ST Unsuccessful |
| 1 | The obje | ctive was achieved | Ouccessial | Orisaccessiai |
| 2 | The resc | euer could perform the required task | | |
| 3 | Fall prote | ection was maintained | | |
| Evaluator/Candidate | | adidate Comments: | | |
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| Cano | lidate: | | | Successful | | |
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| Evalu | uator: | | Uı | nsuccessful | | |
| Date | : | | | 1006-SKILL-37 | | |
| Stan | dard: | NFPA 1006 – 2021 edition – 5.3.8 | | | | |
| Task: | | Interact with a person at height who is in crisis | Interact with a person at height who is in an emotional or psychological crisis | | | |
| Performance Outcome: | | The condition is recognized and communicated to the team, the rescuer is prevented from harm, and the actions of the rescuer do not escalate the incident. | | | | |
| Conditions: | | Given an environment consistent with the policies and procedures of the organization scenario | | • | | |
| Candidate Directive: | | "Provide comfort and instruction to the ag | itated victim". | | | |
| | | | | | | |
| NO. | | TASK STEPS | TE Successful | ST Unsuccessful | | |
| 1 | The cond to the tea | dition was recognized and communicated am | | | | |
| 2 | The reso | cuer was prevented from harm | | | | |
| 3 | The action incident | ons of the rescuer did not escalate the | | | | |
| Evaluator/Candidate Comments: | | | | | | |
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| Evaluator: | Unsuccessful |
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| Date: | 1006-PROCESS-38 |
| Standard: NFPA 1006 – 2021 edition – 5.3.9 | |
| Task: Ascend a fixed rope in a high-angle | environment |
| , | ling is minimized, the person the fixed rope and rest suspended ill not be stressed to the point of convert his or her ascending system are negotiated, the system is |
| Conditions: Given an anchored fixed-rope system the rescuer, a system to allow asce belay system, a life safety harness PPE | • |
| Candidate "Using the provided equipment, fixe ascend the fixed rope". | d rope and high-angle environment, |

| NO. | TASK STEPS | TEST | |
|-----|---|------------|--------------|
| | TASK STEPS | Successful | Unsuccessful |
| 1 | The person ascending was secured to the fixed rope in a manner that would not allow him or her to fall | | |
| 2 | The person ascending was attached to the rope by means of an ascent control device(s) with at least two points of contact | | |
| 3 | Injury to the person ascending was minimized | | |
| 4 | The person ascending could stop at any point on the fixed rope and rest suspended by his or her harness | | |
| 5 | The system would not be stressed to the point of failure | | |





| 6 | The person ascending could convert his or her ascending system to a descending system | | |
|-------------------------------|---|--|--|
| 7 | Obstacles were negotiated | | |
| 8 | The system was suitable for the site | | |
| 9 | The objective was reached | | |
| Evaluator/Candidate Comments: | | | |
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| Candidate: | | Successful |
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| Evaluator: | | Unsuccessful |
| Date: | | 1006-PROCESS-39 |
| Standard: | NFPA 1006 – 2021 edition – 5.3.10 | |
| Task: | Descend a fixed rope in a high-angle environme | nt |
| Performance Outcome: | The person descending is attached to the fixed rope in a manner that will not allow him or her to fall, the person descending is attached to the rope by means of a descent control device, the speed of descent is controlled, injury to the person descending is minimized, the person descending can stop at any point on the fixed rope and rest suspended by his or her harness, the system will not be stressed to the point of failure, the system is suitable for the site, and the objective is reached. | |
| Conditions: | Given an anchored fixed-rope system, a specific distance for the rescuer, a system to allow descended belay system, a life safety harness worn by the page PPE | ent of a fixed rope, a |
| Candidate Directive: | "Using the provided equipment, fixed rope and had descend the fixed rope". | nigh-angle environment, |

| NO. | TACK STEDS | TEST | |
|-----|--|-------------------------|--|
| | TASK STEPS | Successful Unsuccessful | |
| | The person descending was attached to the | | |
| 1 | fixed rope in a manner that would not allow him | | |
| | or her to fall | | |
| 2 | The person descending was attached to the | | |
| | rope by means of a descent control device | | |
| 3 | The speed of descent was controlled | | |
| 4 | Injury to the person descending was minimized | | |
| | The person descending could stop at any point | | |
| 5 | on the fixed rope and rest suspended by his or | | |
| | her harness | | |
| 6 | The system would not be stressed to the point of | | |
| | failure | | |
| 7 | The system was suitable for the site | | |
| 8 | The objective was reached | | |



| Evaluator/Candidate Comments: | | | |
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| Evaluator: | Unsuccessful |] |
| Date: | 1006-SKILL-40 |) |
| Standard: | NFPA 1006 – 2021 edition – 5.3.11 | |
| Task: | Demonstrate the ability to escape from a jammed or malfunctioning device during a fixed-rope descent in a high-angle environment | |
| Performance Outcome: | The person descending is attached to the fixed rope in a manner that will not allow him or her to fall, the person descending is attached to the rope by means of a descent control device, the means for escape will allow the rescuer to escape either upward or downward from the malfunctioning descent control device, injury potential to the rescuer is minimized, the system will not be stressed to the point of failure, the system is suitable for the site, and the objective is reached. | |
| Conditions: | Given an anchored fixed-rope system with a simulated malfunctioning descent control device, a system to allow escape from the malfunctioning device, a belay system, a life safety harness worn by the person descending, and PPE |) |
| Candidate Directive: | "Using the provided equipment, fixed rope and high-angle environment, demonstrate an escape from a jammed or malfunctioning device". | |

| NO. | TASK STEPS | TEST | |
|-----|---|-------------------------|--|
| | TASK STEPS | Successful Unsuccessful | |
| 1 | The person descending was attached to the fixed rope in a manner that would not allow him or her to fall | | |
| 2 | The person descending was attached to the rope by means of a descent control device | | |
| 3 | The means for escape would allow the rescuer to escape either upward or downward from the malfunctioning descent control device | | |
| 4 | Injury potential to the rescuer was minimized | | |
| 5 | The system would not be stressed to the point of failure | | |
| 6 | The system was suitable for the site | | |
| 7 | The objective was reached | | |



| Evaluator/Candidate Comments: | | | |
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